

## **January 2022 Newsletter**

This is a monthly newsletter of updates from OpenRG Experts. For more updates on OpenRG, follow us on Twitter @OpenRG

## Don Boyd

Don is Co-Director of the State and Local Government Finance Project at Rockefeller College, SUNY Albany, and a consultant, Open Source Policy Center.

- Completed, with co-authors, a draft paper on options for public pension plans in deep distress, and on practices for avoiding deep distress.
- Led a virtual session for journalists on public pensions, hosted through the Ravitch Fiscal Reporting Program at the *Craig Newmark Graduate School of Journalism*.
- Completed an analysis of the compensation of California state correctional officers for *Governing for California*.
- Worked with OpenRG Expert Matt Jensen on modeling national and state-by-state impacts of potential federal tax reform proposals.
- Conducted analysis for the *Pew Charitable Trusts* on state tax revenue volatility.
- Worked with colleagues on a proposal for a web-based public pension simulation model.

## Jason DeBacker

Jason is an Associate Professor of economics at the University of South Carolina and a core maintainer of the open source models <u>Cost-of-Capital-Calculator</u>, <u>Tax-Calculator</u>, and <u>OG-USA</u>, which model business taxes and macroeconomic effects of tax policy, respectively.

- Added government infrastructure investment to the OG-Core model
- Submitted paper on the influence of tax preparers on tax compliance decisions of their clients
- Prepared an NIH grant proposal to study the role of cash transfers on vaccine uptake

## Jonathan Pycroft

Jon is an economic modeler and public finance economist based in Seville, Spain. He has experience building and working with computable general equilibrium models, overlapping generations models, and microsimulation models of tax and pension policies in Europe and Africa.

• Delivered simulations of the macroeconomic impacts of changing corporate tax policy deductions for a European Commission study.